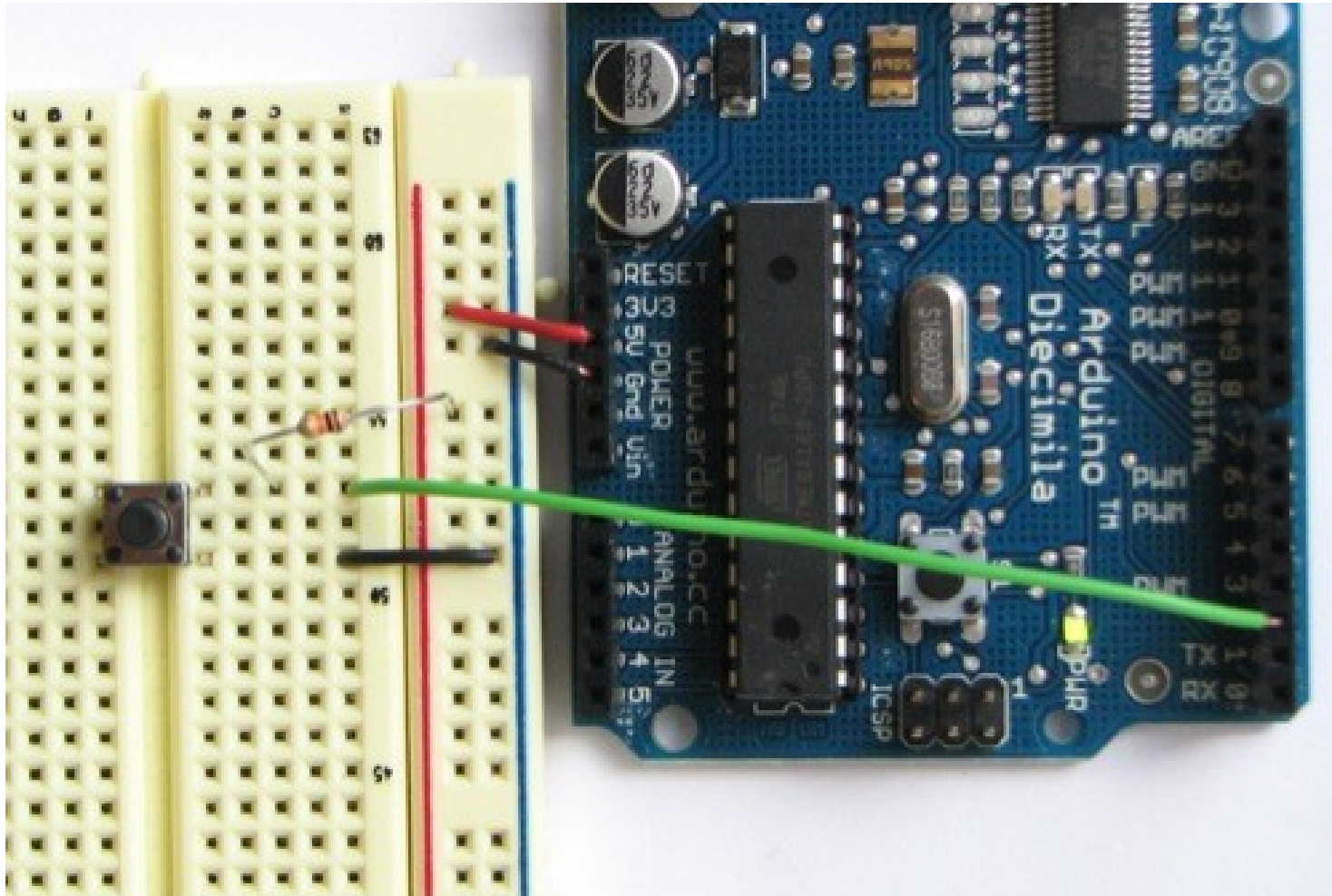


Do-It-Yourself

} buttons and sensors {



Make your own switch

Find this example in:

File > Examples > Digital > Button

<http://www.arduino.cc/en/Tutorial/Button>

Turns on and off a light emitting diode(LED) connected to digital pin 13, when pressing a pushbutton attached to pin 2.

The circuit:

- * LED attached from pin 13 to ground
- * pushbutton attached to pin 2 from +5V
- * 10K resistor attached to pin 2 from ground

```
// constants won't change. They're used here to
// set pin numbers:
const int buttonPin = 2;    // the number of the pushbutton pin
const int ledPin = 13;      // the number of the LED pin

// variables will change:
int buttonState = 0;        // variable for reading the pushbutton status

void setup() {
  // initialize the LED pin as an output:
  pinMode(ledPin, OUTPUT);
  // initialize the pushbutton pin as an input:
  pinMode(buttonPin, INPUT);
}

void loop(){
  // read the state of the pushbutton value:
  buttonState = digitalRead(buttonPin);

  // check if the pushbutton is pressed.
  // if it is, the buttonState is HIGH:
  if (buttonState == HIGH) {
    // turn LED on:
    digitalWrite(ledPin, HIGH);
  }
  else {
    // turn LED off:
    digitalWrite(ledPin, LOW);
  }
}
```

```
const int buttonPin = 2;    // the number of the pushbutton pin
const int ledPin = 13;      // the number of the LED pin

// variables will change:
int buttonState = 0;        // variable for reading the pushbutton status

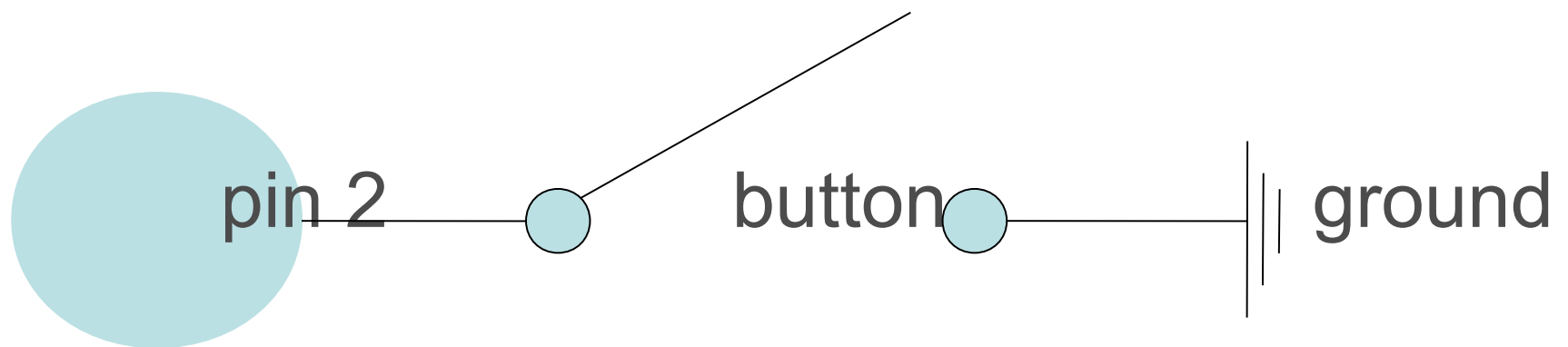
void setup() {
  // initialize the LED pin as an output:
  pinMode(ledPin, OUTPUT);
  // initialize the pushbutton pin as an input:
  pinMode(buttonPin, INPUT);
  digitalWrite(buttonPin, HIGH); //pullup resistors
}

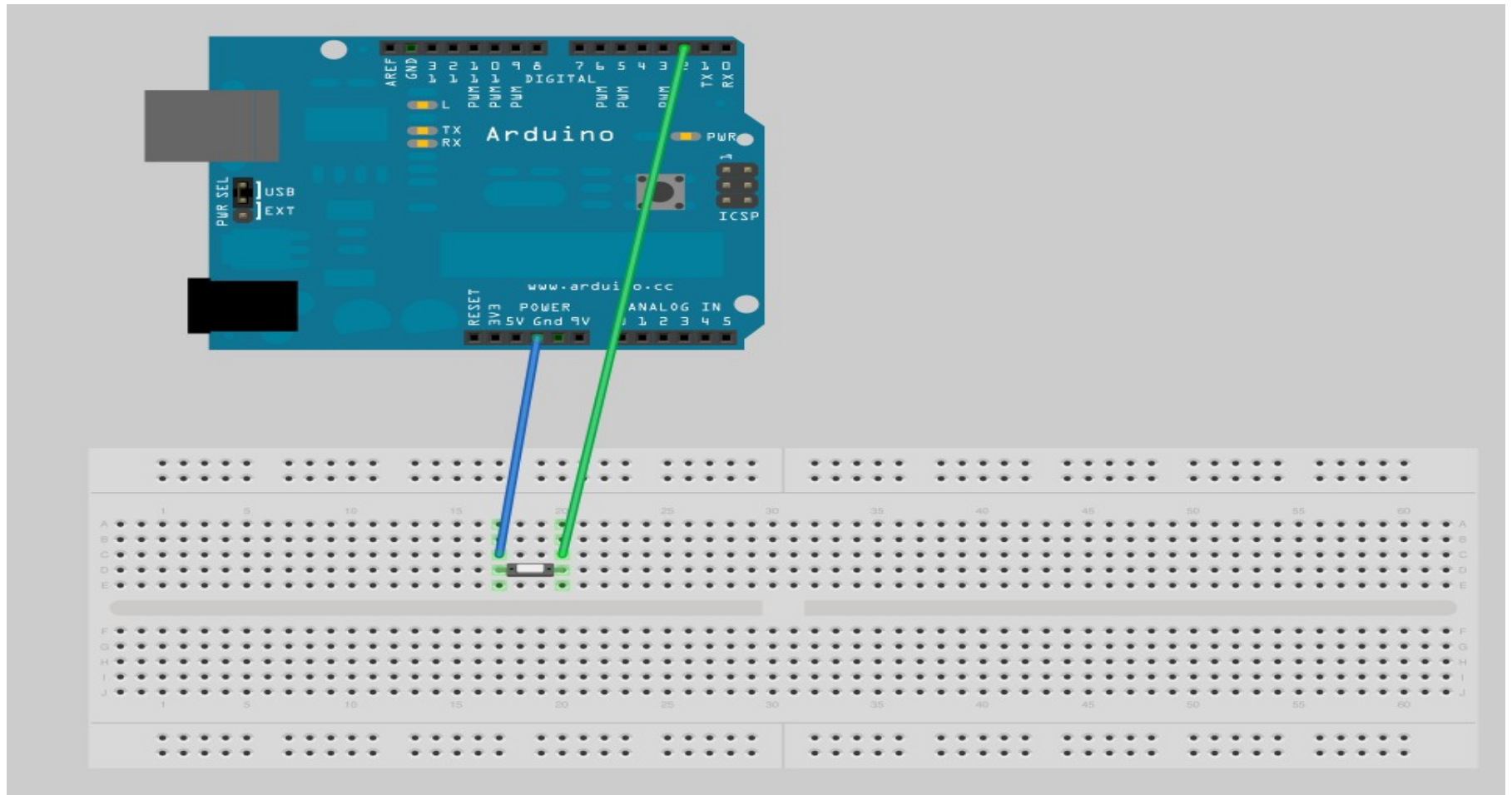
void loop(){
  // read the state of the pushbutton value:
  buttonState = digitalRead(buttonPin);

  // check if the pushbutton is pressed.
  // if it is, the buttonState is HIGH:
  if (buttonState == LOW) {    //pullup to high only to low if button pressed //
    digitalWrite(ledPin, HIGH);
  }
  else {
    // turn LED off:
    digitalWrite(ledPin, LOW);
  }
}
```

your inbuilt resistor is now active

It`s called
PULL UP RESISTOR





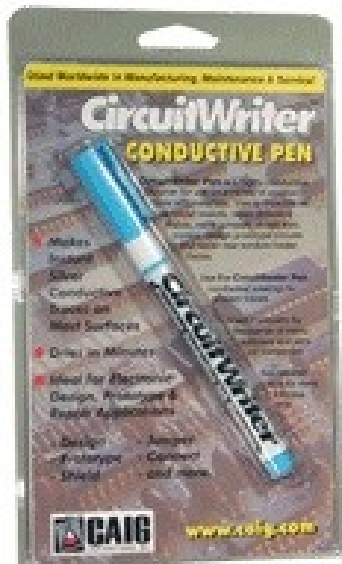
Now you are free to
replace your button with any
conductive material and connect it
temporarily through any thing that
comes to your mind



Leitender Faden



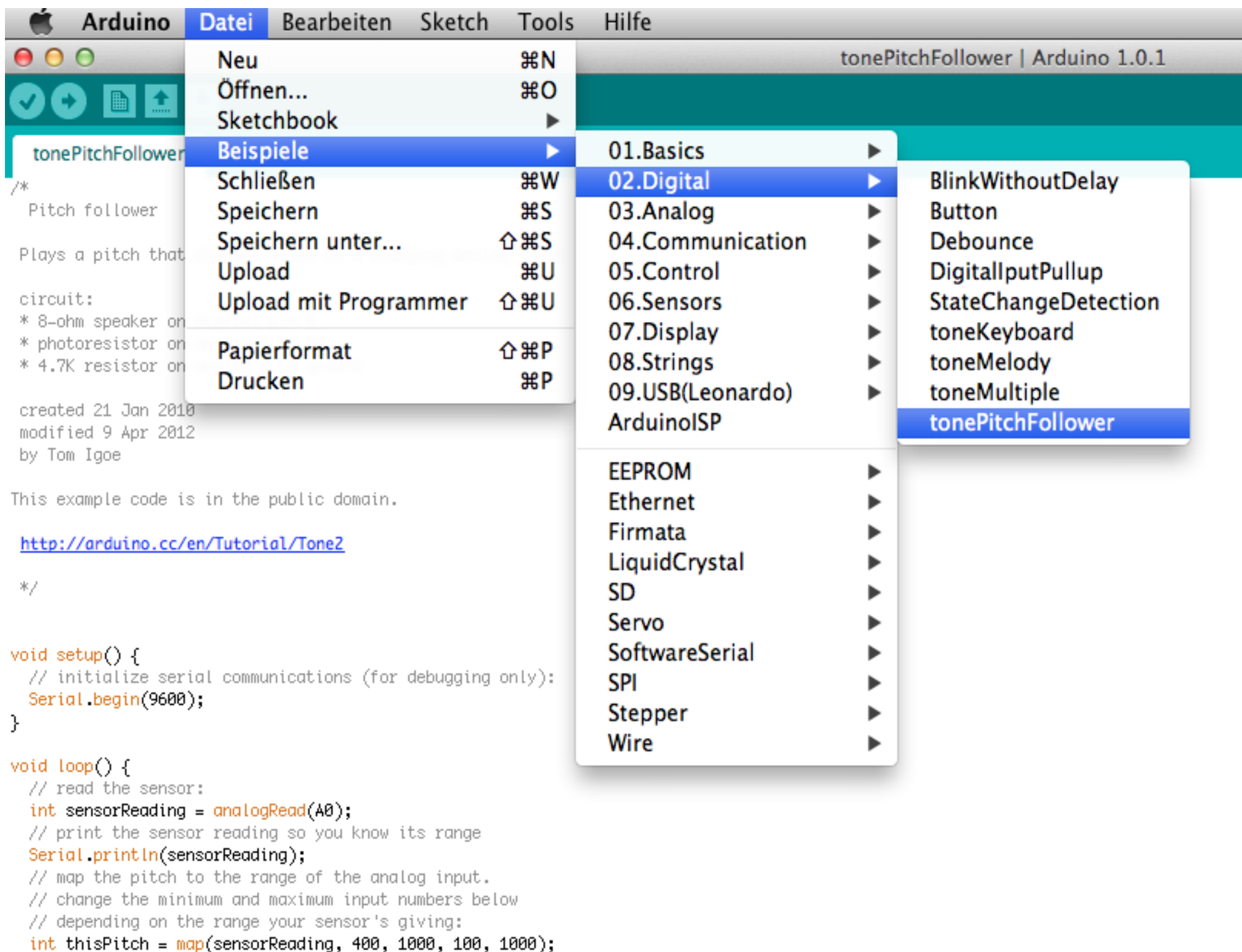
Leitender Stoff

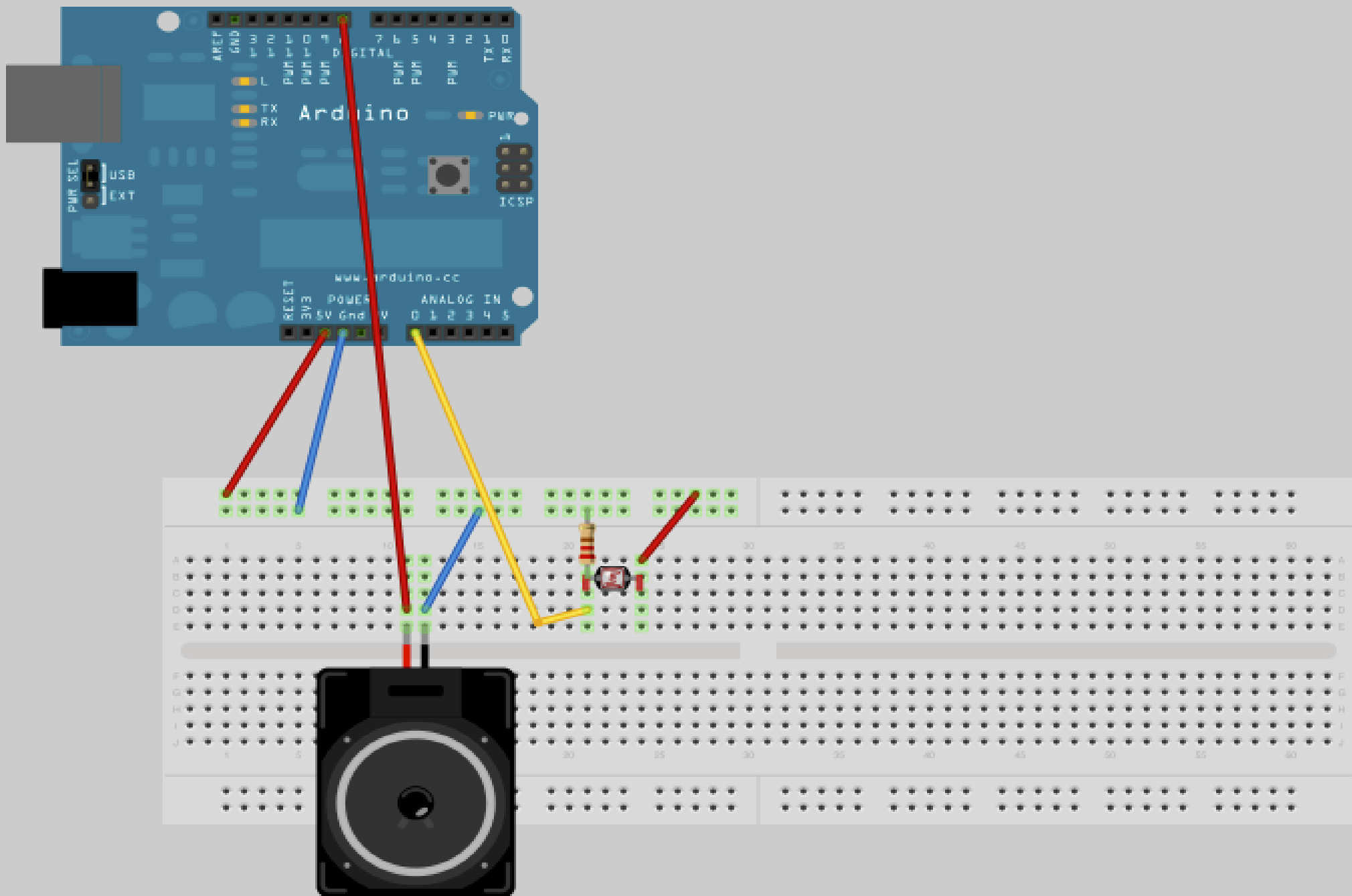


Leitender Lack

Tone Pitch Follower

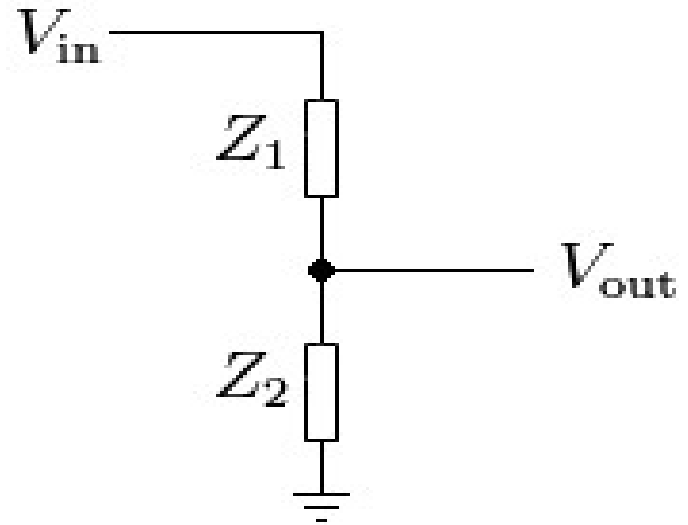
Examples – Digital - TonePitchFollower





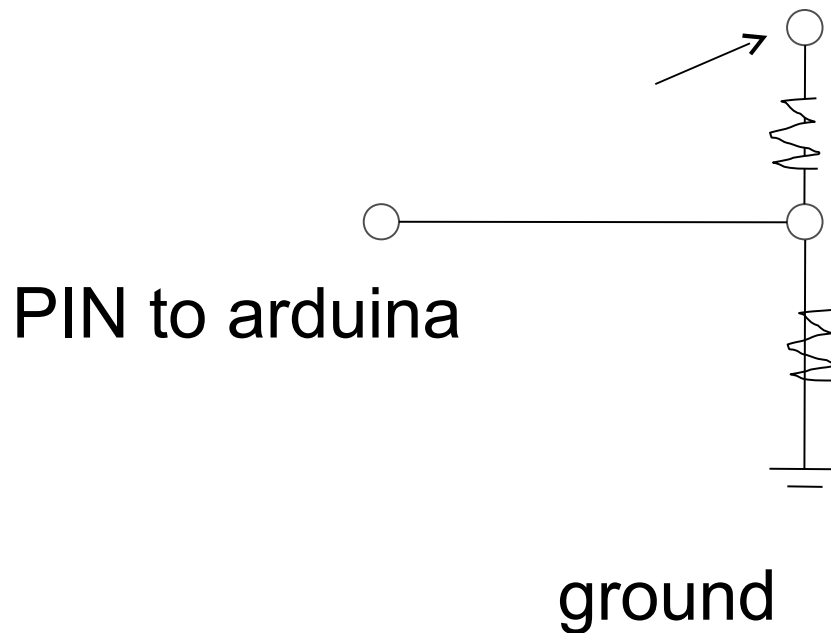
spannungsteiler

$$V_{\text{out}} = \frac{Z_2}{Z_1 + Z_2} \cdot V_{\text{in}}$$



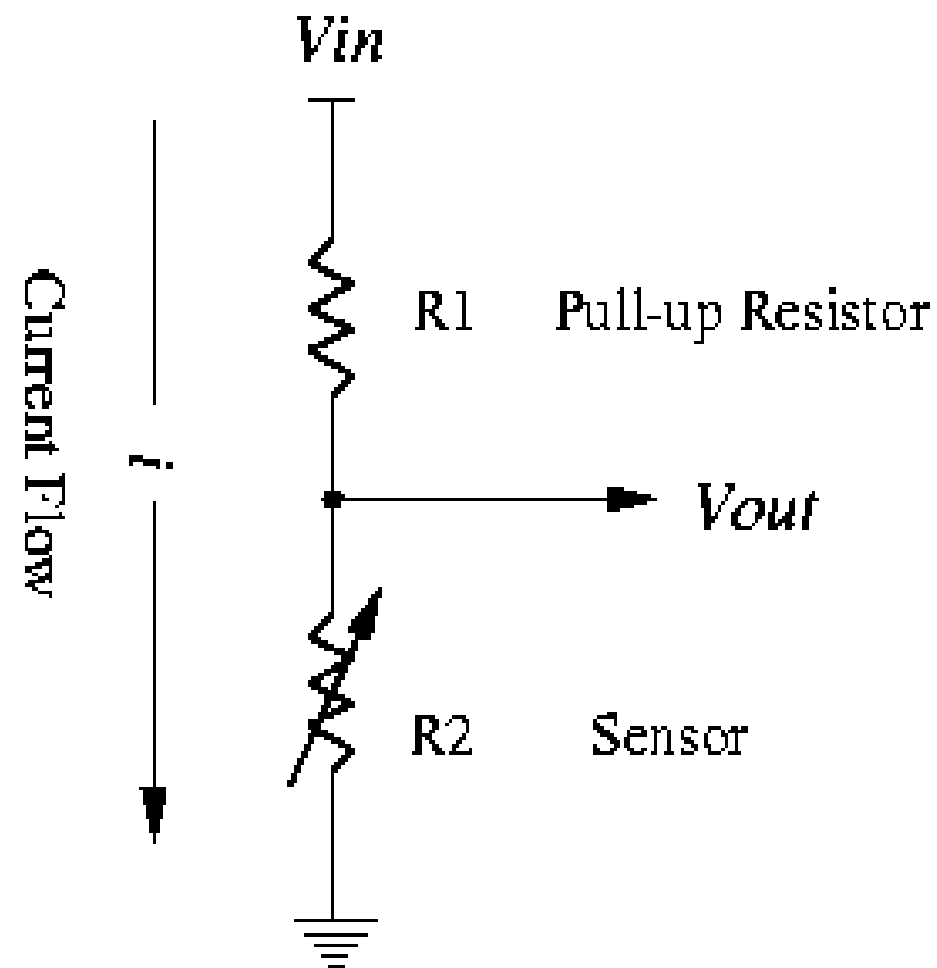
Self made potentiometer

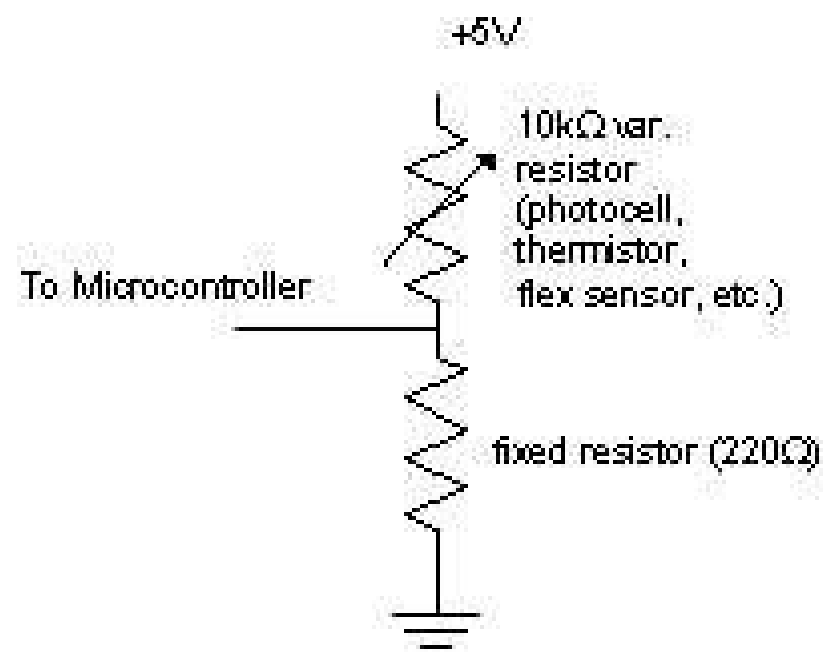
Voltage divider



Variable resistance
from our sensor

Stable resistance
as big as the maximum
resistance
(best you take 2k Ohm)

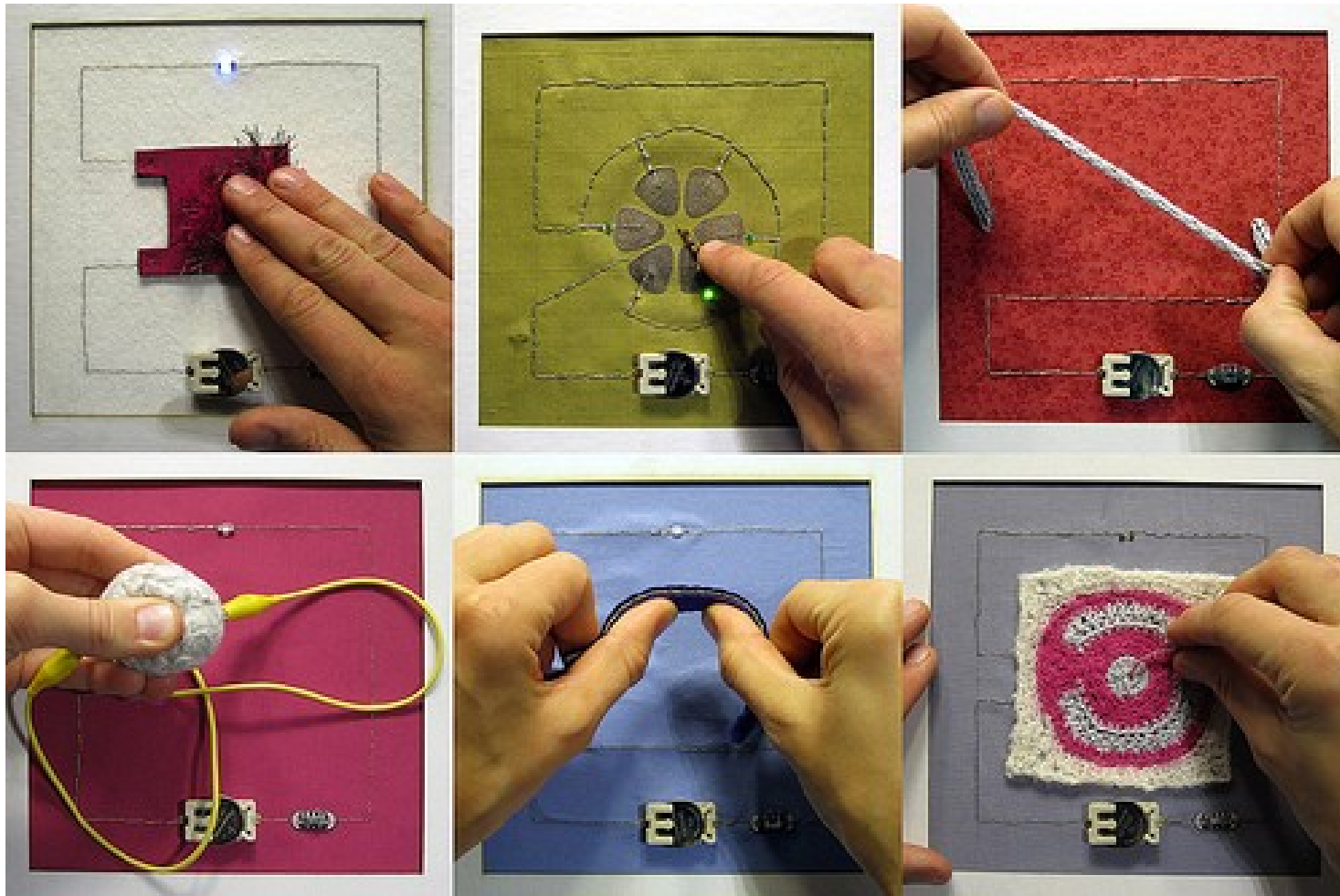






mz baltazar's laboratory

hannah perner wilson



3 LEGS:

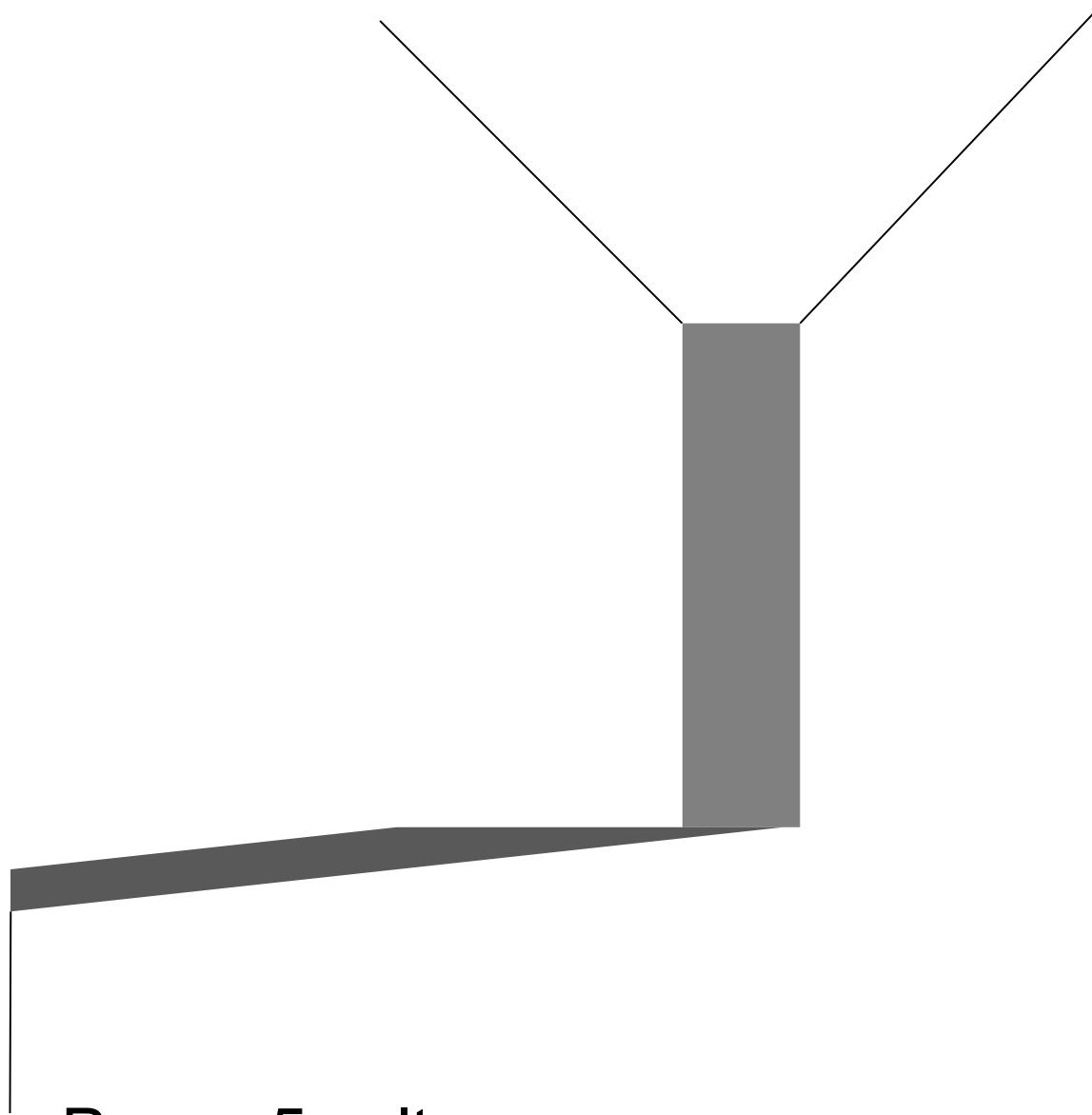
One to power

One through the resistor to ground

One to Arduino Pin „A0“

Pin to Arduina

To ground
through resistor
With
max.
resistance ohm



Power 5 volt

Map

Oberster Wert

Unterster Wert

```
val = map(val, 0, 1023, 0, 179);
```

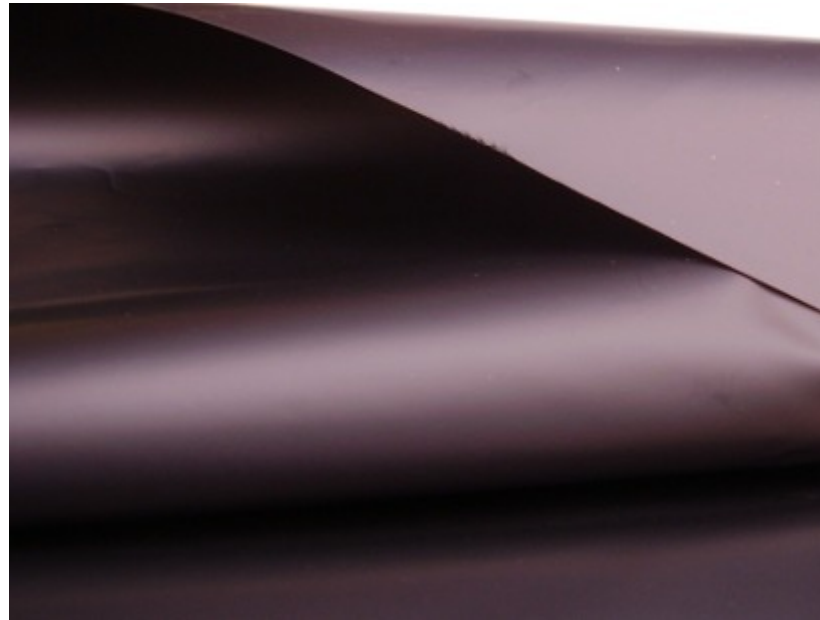
Neuer unterster Wert

Neuer oberster Wert

RESISTIVE MATERIAL

VELOSTAT

**[http://www.plugandwear.com/default.asp?
mod=product&cat_id=89,104&product_id=
136](http://www.plugandwear.com/default.asp?mod=product&cat_id=89,104&product_id=136)**



<http://www.kobakant.at/DIY/?p=381>

Leitender Faden

**[http://www.plugandwear.com/default.asp?
mod=product&cat_id=105&product_id=137](http://www.plugandwear.com/default.asp?mod=product&cat_id=105&product_id=137)**



Leitender Stoff

**[http://www.plugandwear.com/default.asp?
mod=product&cat_id=89,104&product_id
=138](http://www.plugandwear.com/default.asp?mod=product&cat_id=89,104&product_id=138)**

www.physicalcomputing.at



possible materials to use as potentiometers



Videotape



Graphite

Graphite

KILO OHM

300

500

600

700

1000

1200

1500

1600

1700

300k
ohm

500k
ohm

600k
ohm

700k
ohm

1000k
ohm

1200k
ohm

1500k
ohm

1600k
ohm

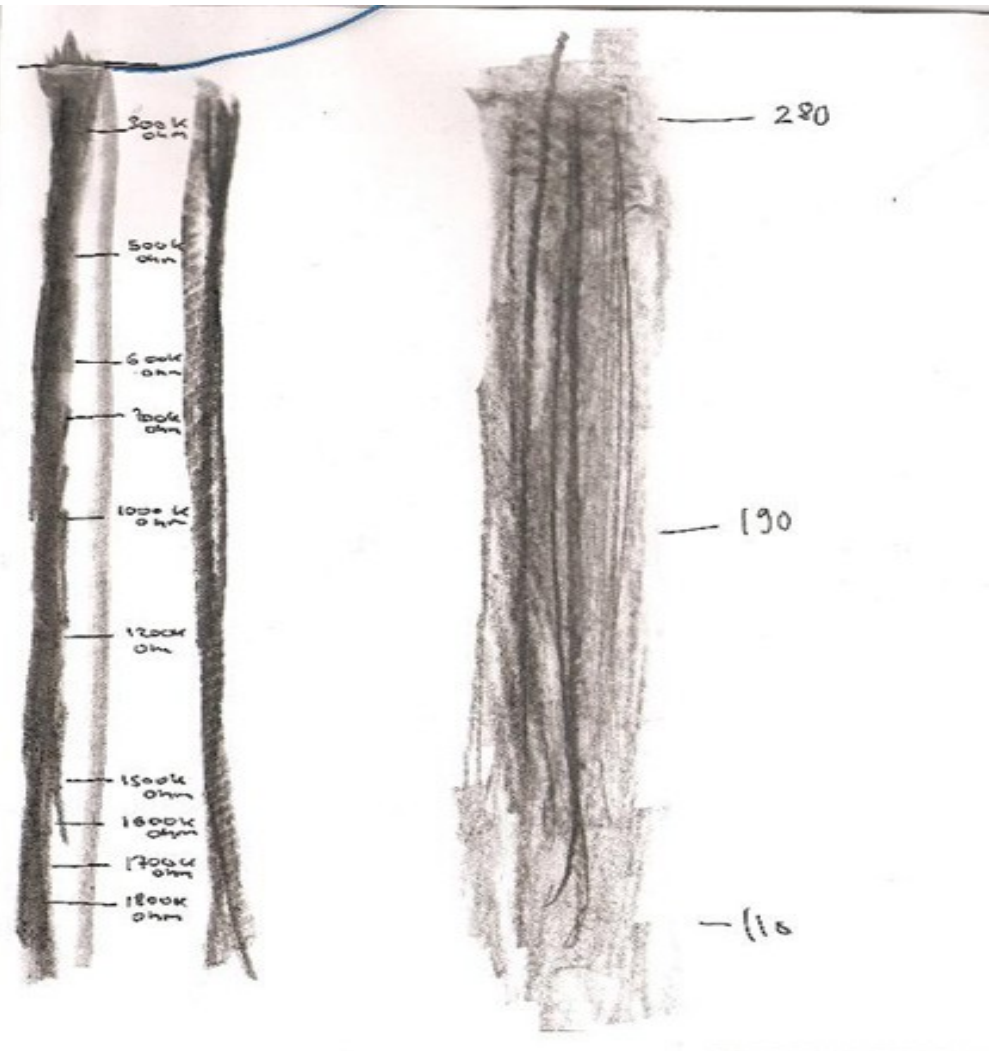
1700k
ohm

1800k
ohm

280

190

110



100k Ω -

200k Ω -

300k Ω -

400k Ω -

500k Ω -

600k Ω -

700k Ω -

800k Ω -

900k Ω -

50 Ω -

30,0 Ω -

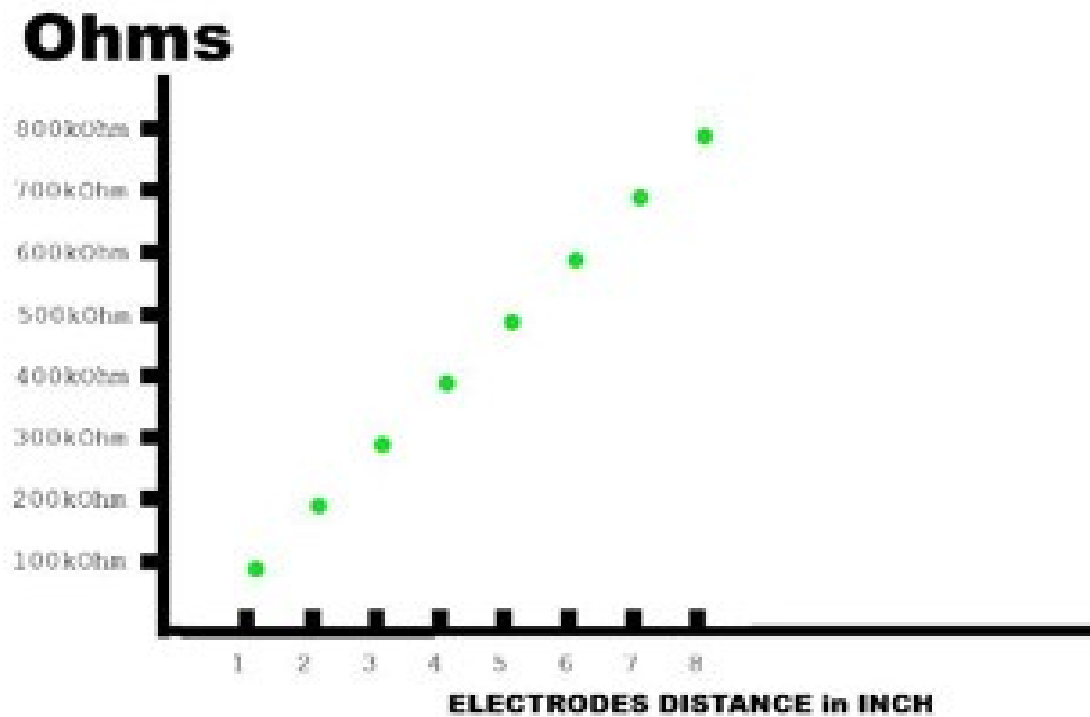
50,0 Ω -

50,0 Ω -

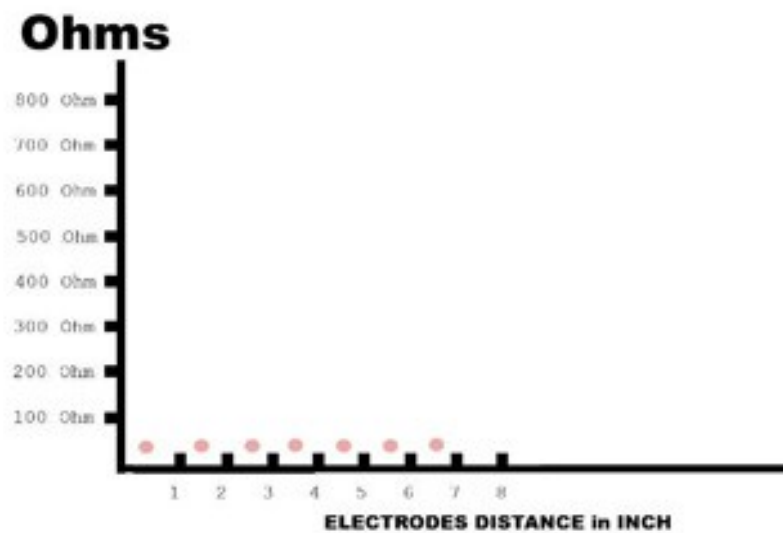
35,0 Ω -

40,0 Ω -

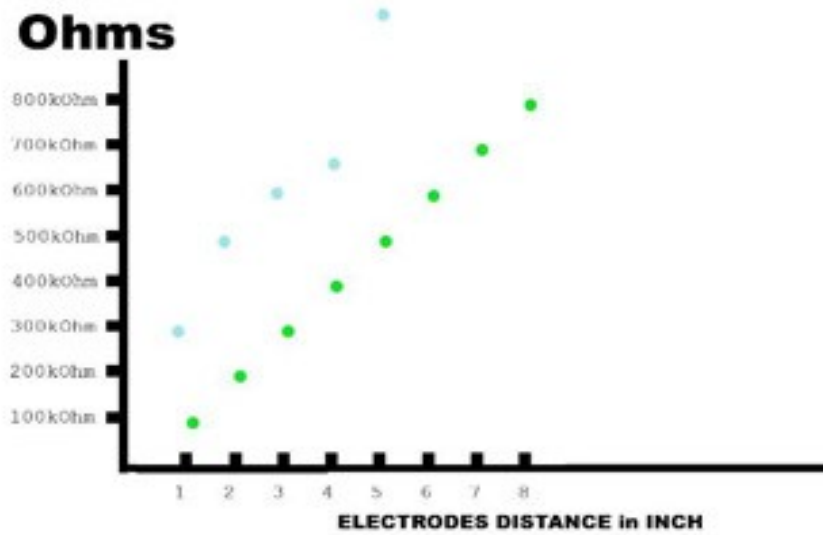
Only valid for video tape produced before 1996



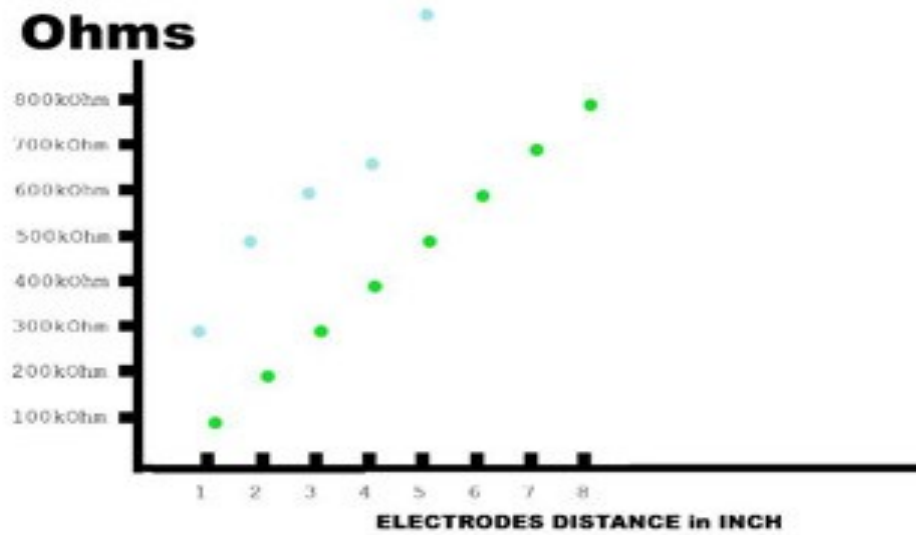
Conductive Ink 30 - 50 Ohms
Disadvantage: no uniformed conductivity



Graphite vs. Videotape

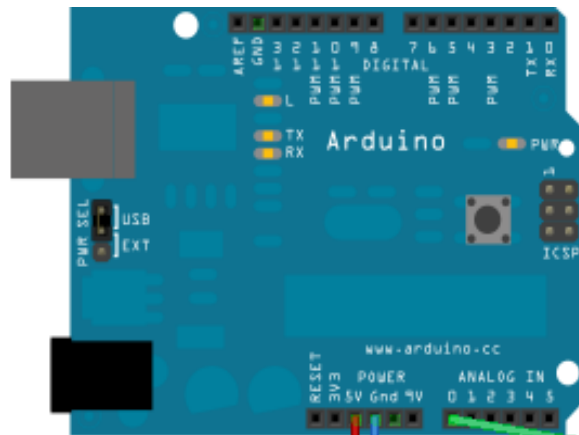


Graphite vs. Videotape



graphit

DIY ANALOG SENSOR / VARIABLE RESISTOR



Ground zu
Breadboard

5 Volt zu Breadboard

Daten über sich verändernden
Widerstand gehen von hier zu
Arduino (zu Pin Analog 0):
Beweglich

leitende Fläche mit, sich durch
Distanz vergrößerndem,
Widerstand

Widerstand zwischen Sensor
und Ground muss so groß sein,
wie der niedrigste Widerstand
des Sensors (Spannungsteiler)

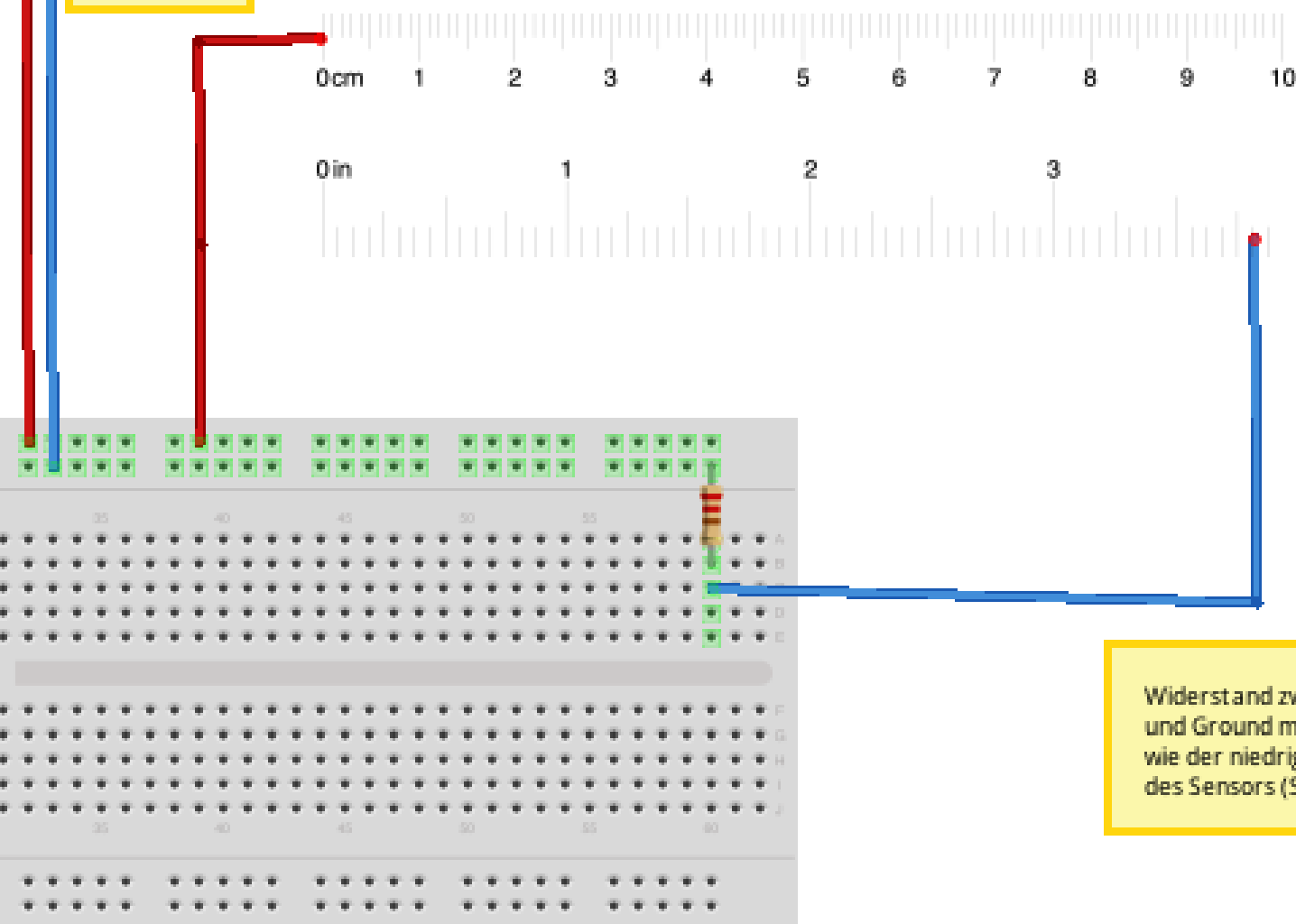


Ground zu
Breadboard

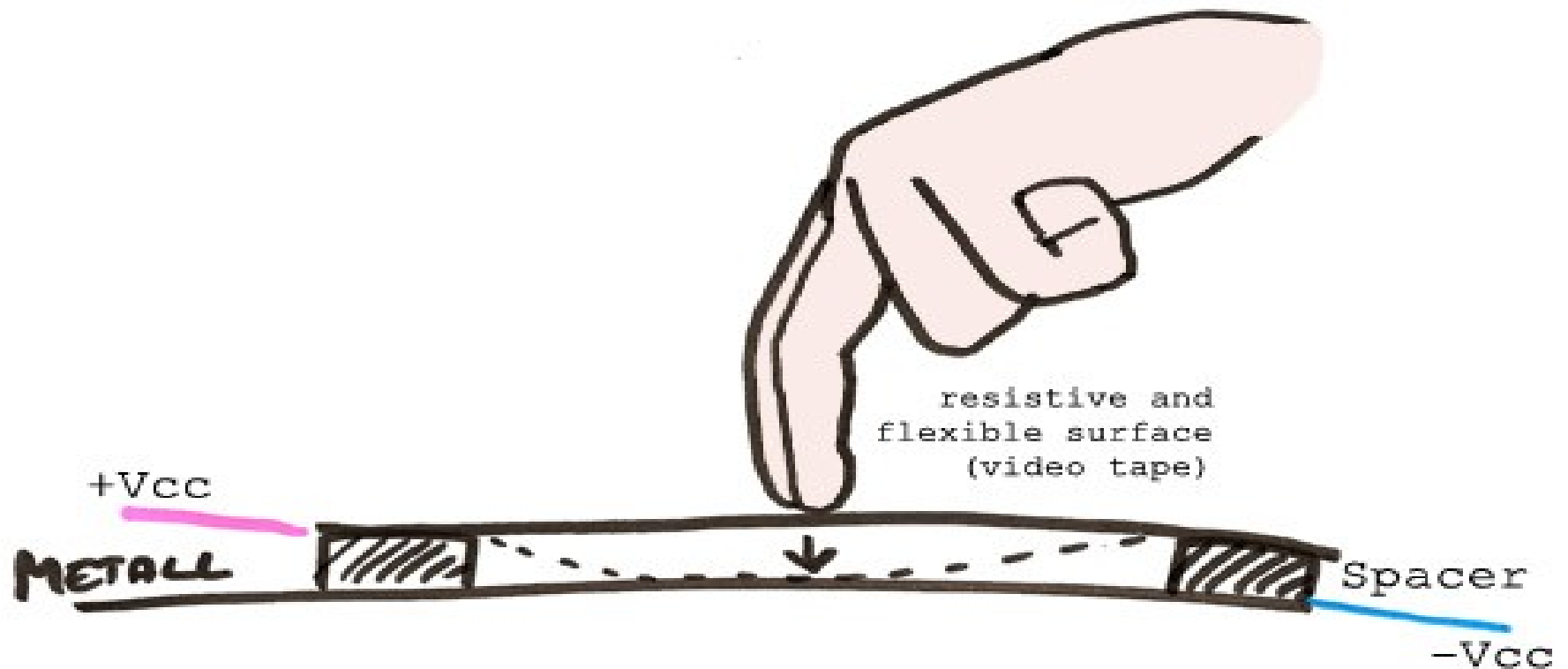
Daten über sich verändernden
Widerstand gehen von hier zu
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Beweglich

leitende Fläche mit, sich durch
Distanz vergrößerndem,
Widerstand

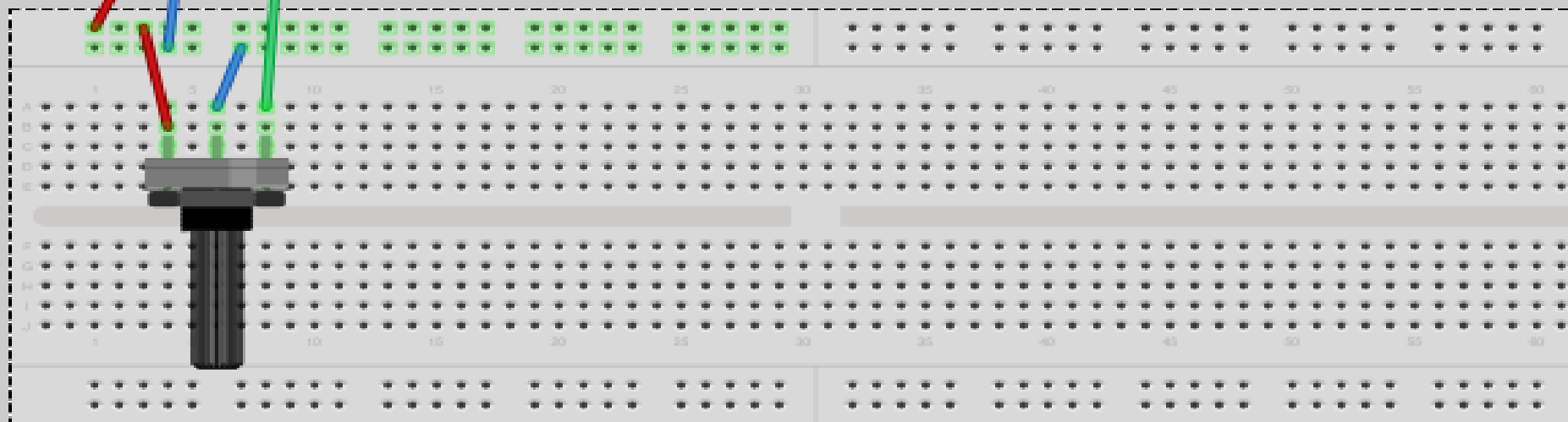
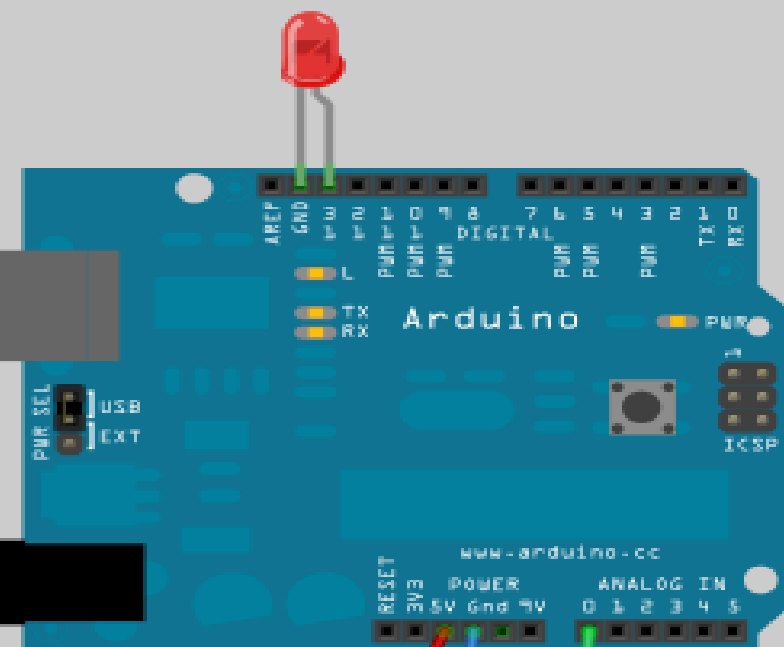
Widerstand zwischen Sensor
und Ground muss so groß sein,
wie der niedrigste Widerstand
des Sensors (Spannungsteiler)



Touch sensor



MESSGERÄT FÜR SELBST GEMACHTE SENSOREN



Arduino Code

Examples – Analog - AnalogInOutSerial

```
constants won't change. They're used to give names
pins used:
analogInPin = A0; // Analog input pin that the potentiometer is attached to
analogOutPin = 9; // Analog output pin that the LED is attached to

int sensorValue = 0; // value read from the pot
int outputValue = 0; // value output to the PWM (analog out)

void setup() {
  // Initialize serial communications at 9600 bps:
  Serial.begin(9600);

  // Initialize the pins that will be used:
  pinMode(analogInPin, INPUT);
  pinMode(analogOutPin, OUTPUT);

  // Initialize the LED:
  pinMode(LED_BUILTIN, OUTPUT);

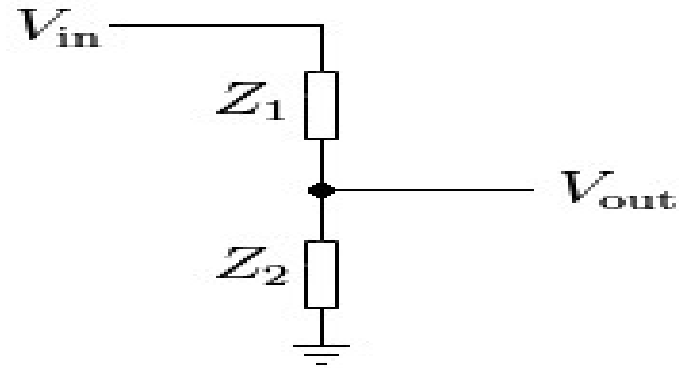
  // Initialize the potentiometer:
  pinMode(POT, INPUT);
}

void loop() {
  // Read the analog in value:
  sensorValue = analogRead(analogInPin);
  // Map the sensor value to the range of the analog out:
  outputValue = map(sensorValue, 0, 1023, 0, 255);
  // Write the analog out value:
  analogWrite(analogOutPin, outputValue);

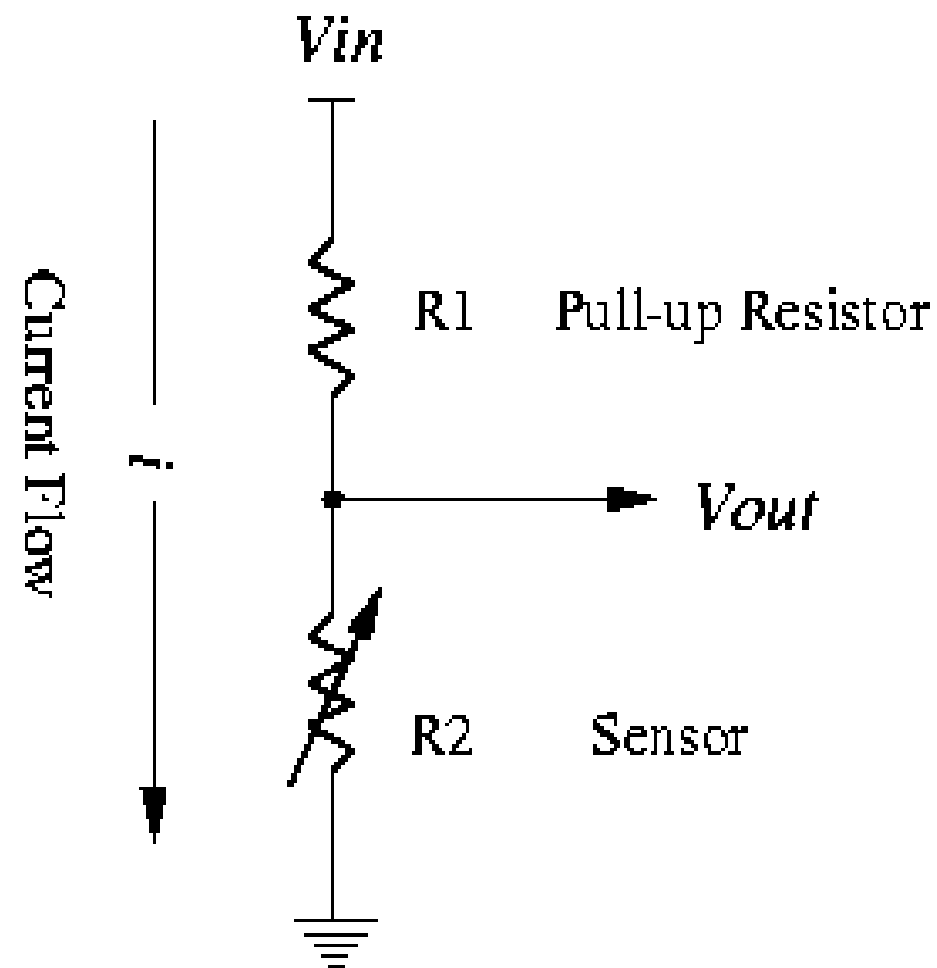
  // Print the results to the serial monitor:
  Serial.print("sensor = ");
  Serial.print(sensorValue);
  Serial.print("\t output = ");
  Serial.println(outputValue);

  // Wait 1000 milliseconds before the next loop
  // to give the analog-to-digital converter time to settle
  // the last reading:
  delay(1000);
}
```

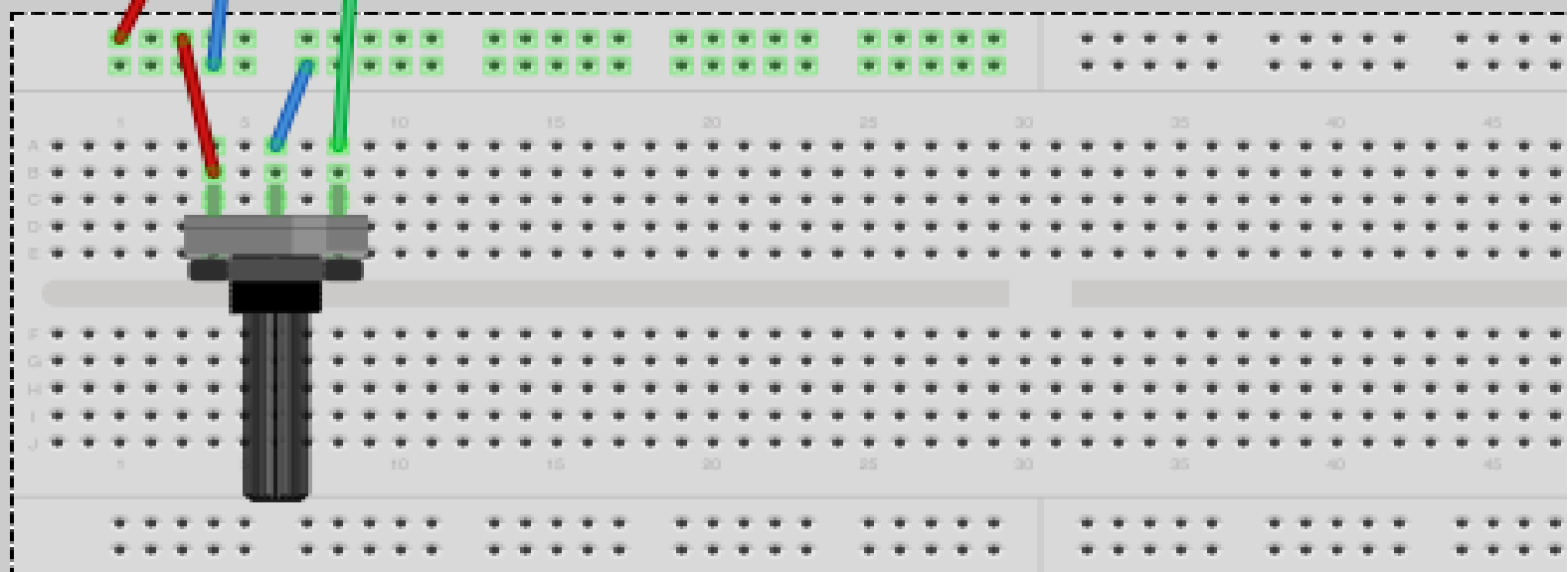
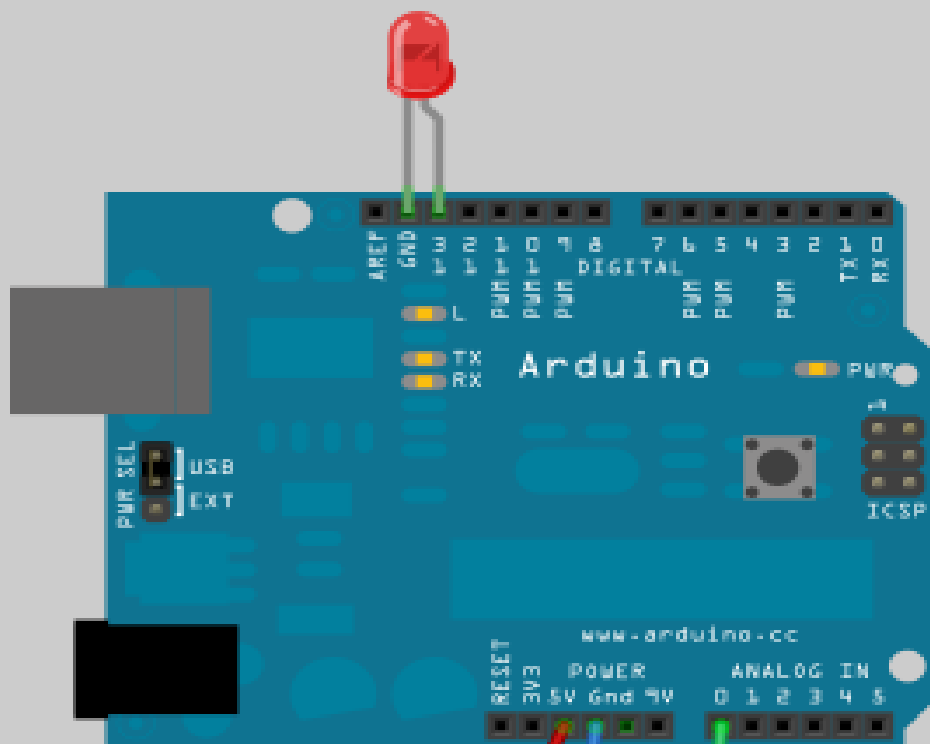
spannungsteiler



$$V_{out} = \frac{Z_2}{Z_1 + Z_2} \cdot V_{in}$$



FOR LOOP
WHILE LOOP



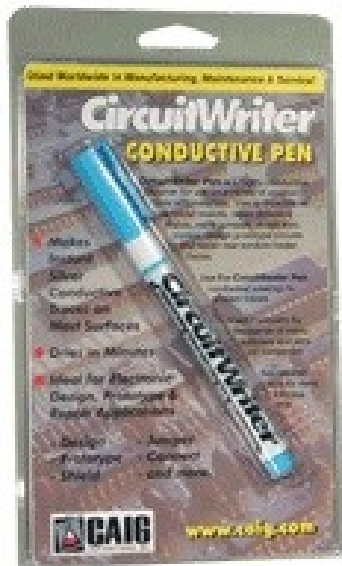

```
outputValue = map(sensorValue, 0, 1023, 0, 255);
```



Leitender Faden



Leitender Stoff



Leitender Lack

VELOSTAT

**[http://www.plugandwear.com/default.asp?
mod=product&cat_id=89,104&product_id=
136](http://www.plugandwear.com/default.asp?mod=product&cat_id=89,104&product_id=136)**



Leitender Faden

**[http://www.plugandwear.com/default.asp?
mod=product&cat_id=105&pr
oduct_id=137](http://www.plugandwear.com/default.asp?mod=product&cat_id=105&product_id=137)**



Leitender Stoff

**[http://www.plugandwear.com/default.asp?
mod=product&cat_id=89,104&product_id
=138](http://www.plugandwear.com/default.asp?mod=product&cat_id=89,104&product_id=138)**

www.physicalcomputing.at



possible materials to use as potentiometers



Videotape



Graphite

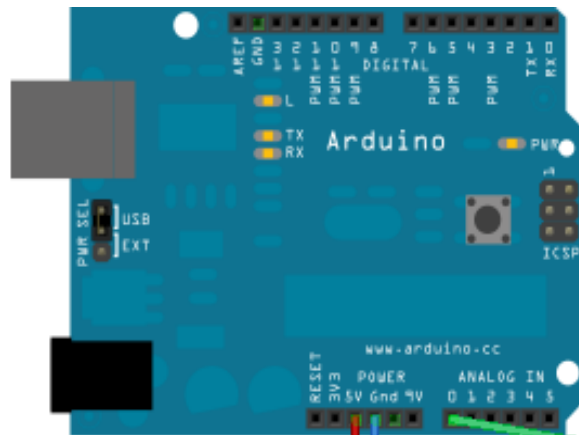
Pressure Sensor

Plastik (Isolating material)

Velostat

Plastik (Isolating material)

DIY ANALOG SENSOR / VARIABLE RESISTOR



Ground zu
Breadboard

5 Volt zu Breadboard

Daten über sich verändernden
Widerstand gehen von hier zu
Arduino (zu Pin Analog 0):
Beweglich

leitende Fläche mit, sich durch
Distanz vergrößerndem,
Widerstand

Widerstand zwischen Sensor
und Ground muss so groß sein,
wie der niedrigste Widerstand
des Sensors (Spannungsteiler)

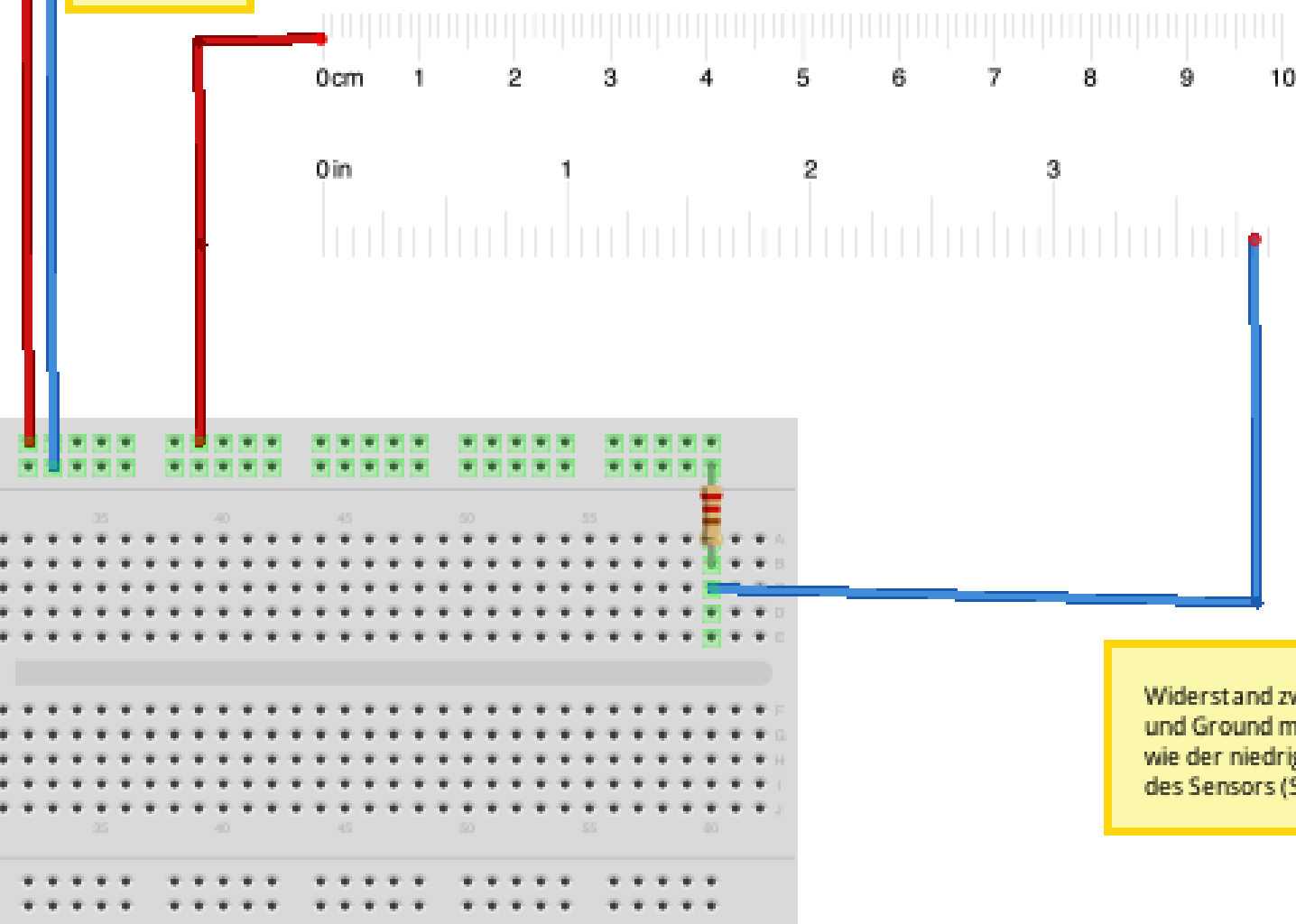


Ground zu
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Daten über sich verändernden
Widerstand gehen von hier zu
Arduino (zu Pin Analog 0) :
Beweglich

leitende Fläche mit, sich durch
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Widerstand zwischen Sensor
und Ground muss so groß sein,
wie der niedrigste Widerstand
des Sensors (Spannungsteiler)



LOOPS

out of the Book:

30 Arduino Projects for the Evil Genius

YOU FIND THIS EXAMPLE ONLINE:

<http://arduino.cc/en/Tutorial/ForLoop>

Loops allow us to repeat a group of commands a certain number of times or until some condition is met.

DESCRIPTION

The for statement is used to repeat a block of statements enclosed in curly braces.

An increment counter (ZÄHLER) is usually used to increment and terminate the loop.

The for statement is useful for any repetitive operation,

and is often used in combination with arrays to operate on collections of data/pins.

There are three parts to the for loop header:

```
for (initialization; condition; increment) {
```

```
//statement(s);
```

```
}
```

SYNTAX OF A FOR LOOP

parenthesis

declare variable (optional)

initialize

test

increment or
decrement

```
for(int x = 0; x < 100; x++) {  
    println(x); // prints 0 to 99  
}
```

The diagram illustrates the syntax of a for loop with the following components and their corresponding labels:

- parenthesis**: Points to the opening and closing curly braces of the loop.
- declare variable (optional)**: Points to the variable declaration `int x`.
- initialize**: Points to the initialization expression `= 0`.
- test**: Points to the test expression `x < 100`.
- increment or decrement**: Points to the increment/decrement expression `x++`.

The initialization happens first and exactly once.
Each time through the loop, the condition is tested;

if it's true, the statement block, and the increment is executed, then the condition is tested again.

When the condition becomes false, the loop ends.

Another example, fade an LED up and down with one for loop:

```
void loop()  
{  
    int x = 1;  
    for (int i = 0; i > -1; i = i + x){  
        analogWrite(PWMpin, i);  
        if (i == 255) x = -1;           // switch direction at peak  
        delay(10);  
    }  
}
```

```
// loop from the lowest pin to the highest:
for (int thisPin = 2; thisPin < 8; thisPin++) {
    // turn the pin on:
    digitalWrite(thisPin, HIGH);
    delay(timer);
    // turn the pin off:
    digitalWrite(thisPin, LOW);
}
```

Another way of looping in C is to use the while command.

```
while (digitalRead(buttonPin) == HIGH) {  
    calibrate();  
}
```

WHILE COMMAND

DESCRIPTION

while loops will loop continuously,
and infinitely,
until the expression inside the parenthesis, ()
becomes false.

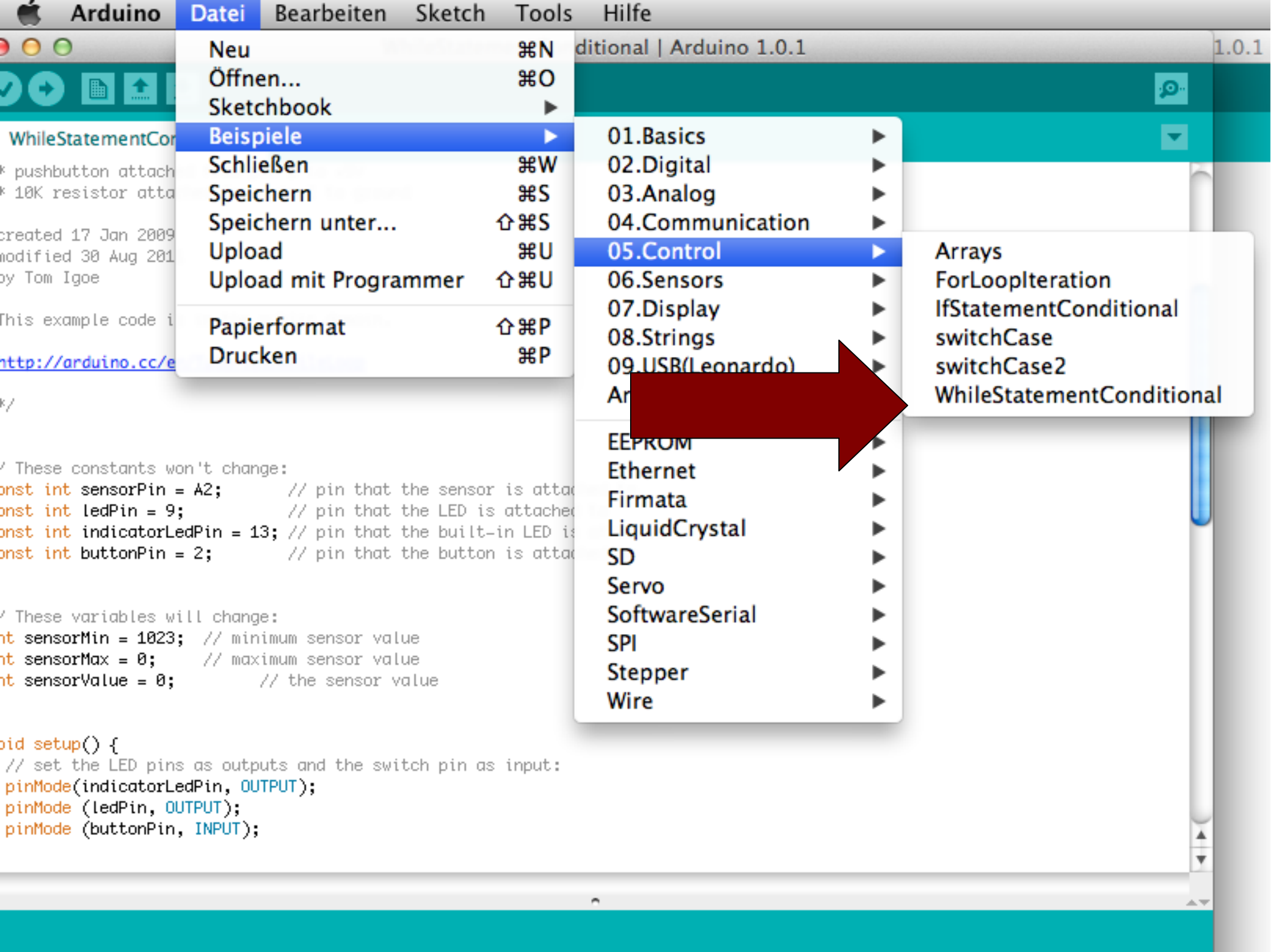
Something must change the tested variable, or the while loop will never exit.

This could be in your code, such as an incremented variable, or an external condition, such as testing a sensor.

SYNTAX

```
while(expression){  
    // statement(s)  
}
```

```
While your are in my house {  
You can eat as much chocolate as you like  
}
```

- Neu ⌘N
- Öffnen... ⌘O
- Sketchbook ▶
- Beispiele ▶**
- Schließen ⌘W
- Speichern ⌘S
- Speichern unter... ⇧⌘S
- Upload ⌘U
- Upload mit Programmer ⇧⌘U
- Papierformat ⇧⌘P
- Drucken ⌘P

- 01.Basics ▶
- 02.Digital ▶
- 03.Analog ▶
- 04.Communication ▶
- 05.Control ▶**
- 06.Sensors ▶
- 07.Display ▶
- 08.Strings ▶
- 09.USB(Leonardo) ▶
- Ar...

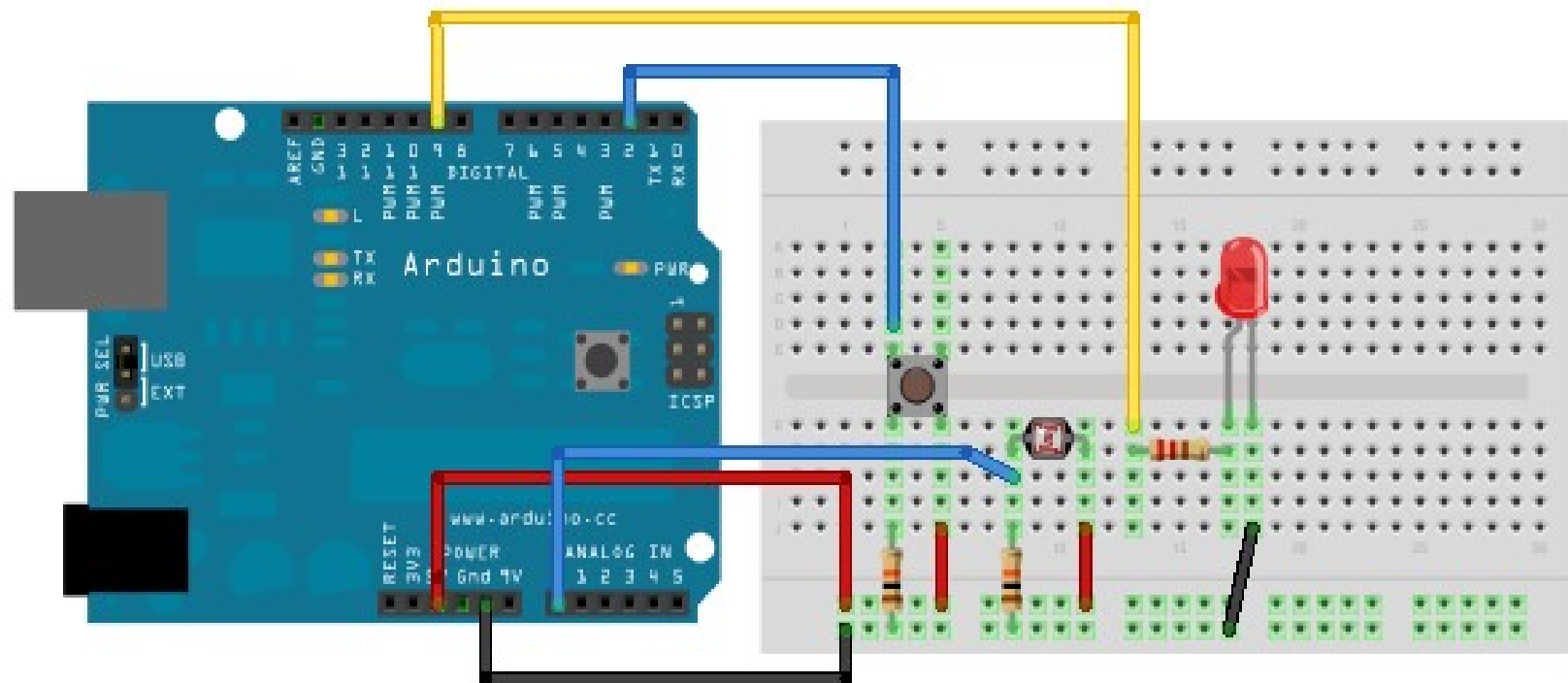
- Arrays
- ForLoopIteration
- IfStatementConditional
- switchCase
- switchCase2
- WhileStatementConditional**

```
// These constants won't change:
const int sensorPin = A2;    // pin that the sensor is attached to
const int ledPin = 9;        // pin that the LED is attached to
const int indicatorLedPin = 13; // pin that the built-in LED is attached to
const int buttonPin = 2;     // pin that the button is attached to

// These variables will change:
int sensorMin = 1023; // minimum sensor value
int sensorMax = 0;    // maximum sensor value
int sensorValue = 0;  // the sensor value

void setup() {
  // set the LED pins as outputs and the switch pin as input:
  pinMode(indicatorLedPin, OUTPUT);
  pinMode(ledPin, OUTPUT);
  pinMode(buttonPin, INPUT);
}
```

<http://arduino.cc/en/Tutorial/WhileLoop>





The expression in parentheses after while must be true to stay in the loop. When it is no longer true, the sketch will continue running the commands after the final curly brace.

The curly braces are used to bracket together a group of commands. In programming parlance, they are known as a block.

```
// These constants won't change:
const int sensorPin = A2;      // pin that the sensor is attached to
const int ledPin = 9;          // pin that the LED is attached to
const int indicatorLedPin = 13; // pin that the built-in LED is attached to
const int buttonPin = 2;       // pin that the button is attached to


// These variables will change:
int sensorMin = 1023; // minimum sensor value
int sensorMax = 0;    // maximum sensor value
int sensorValue = 0;  // the sensor value


void setup() {
  // set the LED pins as outputs and the switch pin as input:
  pinMode(indicatorLedPin, OUTPUT);
  pinMode (ledPin, OUTPUT);
  pinMode (buttonPin, INPUT);
}
```

```
void loop() {  
  // while the button is pressed, take calibration readings:  
  while (digitalRead(buttonPin) == HIGH) {  
    calibrate();  
  }  
  // signal the end of the calibration period  
  digitalWrite(indicatorLedPin, LOW);  
  
  // read the sensor:  
  sensorValue = analogRead(sensorPin);  
  
  // apply the calibration to the sensor reading  
  sensorValue = map(sensorValue, sensorMin, sensorMax, 0, 255);  
  
  // in case the sensor value is outside the range seen during calibration  
  sensorValue = constrain(sensorValue, 0, 255);  
  
  // fade the LED using the calibrated value:  
  analogWrite(ledPin, sensorValue);  
}
```

```
void calibrate() {  
    // turn on the indicator LED to indicate that calibration is happening:  
    digitalWrite(indicatorLedPin, HIGH);  
    // read the sensor:  
    sensorValue = analogRead(sensorPin);  
  
    // record the maximum sensor value  
    if (sensorValue > sensorMax) {  
        sensorMax = sensorValue;  
    }  
  
    // record the minimum sensor value  
    if (sensorValue < sensorMin) {  
        sensorMin = sensorValue;  
    }  
}
```

**THIS IS OUR TOOL
TO MEASURE
OUR SELF MADE
SENSORS NOW**

